Step Motor (Servo/24 VDC)

Electric Rotary Table

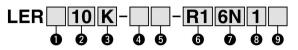
LER Series LER10, 30, 50

(6 c**%** us

RoHS

How to Order

Refer to page 410-1 for the communication protocols EtherCAT®, EtherNet/IP™, PROFINET, DeviceNet™, and IO-Link.



Applicable to the LEC□ series

	Table accuracy				
Nil		Basic type			
	Н	High precision type			

2 Siz	е
10	
30	
50	

Max. rotating torque [N⋅m]

O					
Symbol	Type	LER10	LER30	LER50	
K	High torque	0.32	1.2	10	
J	Basic	0.22	0.8	6.6	

A Rotation angle [°]

Symbol	LER10	LER30	LER50	
Nil	310	320		
2	Exte	rnal stopper:	180	
3	External stopper: 90			

Motor cable entry

C motor casic citary				
	Basic type (entry on the right side)			
Nil				
L	Entry on the left side			

Controller/Driver type*1

Nil	Without controller/driver		
6N	LECP6	NPN	
6P	6P (Step data input type)		
1N	1N LECP1		
1P	1P (Programless type)		
MJ	LECPMJ*2		
IVIJ	(CC-Link direct input type)		
AN	AN LECPA*3		
AP	(Pulse input type)	PNP	

- *1 For details about controller/driver and compatible motor, refer to the compatible controller/driver below.
- *2 Not applicable to CE.
- *3 When pulse signals are open collector, order the current limiting resistor (LEC-PA-R-) on page 596 separately.

Actuator cable type/length

taator babic typericingtii		
Without cable	R5	Robotic cable 5 m
Standard cable 1.5 m	R8	Robotic cable 8 m*1
Standard cable 3 m	RA	Robotic cable 10 m*1
Standard cable 5 m	RB	Robotic cable 15 m*1
Robotic cable 1.5 m	RC	Robotic cable 20 m*1
Robotic cable 3 m		
	Without cable Standard cable 1.5 m Standard cable 3 m Standard cable 5 m Robotic cable 1.5 m	Without cable R5 Standard cable 1.5 m R8 Standard cable 3 m RA Standard cable 5 m RB Robotic cable 1.5 m RC

- *1 Produced upon receipt of order (Robotic cable only) *2 The standard cable should only be used on fixed parts.
- For use on moving parts, select the robotic cable.

1/O cable length [m]*1. Communication plug

Nil	Without cable (Without communication plug connector)*3		
1	1.5		
3	3*2		
5	5* ²		
S	Straight type communication plug connector*		
T	T-branch type communication plug connector*3		

- *1 When "Without controller/driver" is selected for controller/driver types, I/O cable cannot be selected. Refer to page 568 (For LECP6), page 582 (For LECP1) or page 596 (For LECPA) if I/O cable is required.
- *2 When "Pulse input type" is selected for controller/driver types, pulse input usable only with differential. Only 1.5 m cables usable with open collector.
- *3 For the LECPMJ, only "Nil", "S" and "T" are selectable since I/O cable is not included.

Compatible Controller/Driver

Controller/Driver mounting

•	introduct/Direct infoanting
Nil	Screw mounting
D	DIN rail mounting*

* DIN rail is not included. Order it separately.

[CE-compliant products]

- 1) EMC compliance was tested by combining the electric actuator LER series and the controller LEC series.
- The EMC depends on the configuration of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore, conformity to the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result, it is necessary for the customer to verify conformity to the EMC directive for the machinery and equipment as a whole.
- ② CC-Link direct input type (LECPMJ) is not CE-compliant. [UL-compliant products]

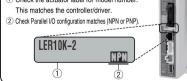
When conformity to III is required the electric actuator and controller/driver should be used with a UL1310 Class 2 power supply.

The actuator and controller/driver are sold as a package.

Confirm that the combination of the controller/driver and the actuator is correct.

<Check the following before use.>

1) Check the actuator label for model number. This matches the controller/driver



Refer to the operation manual for using the products. Please download it via our website, http://www.smcworld.com

Pulse input Step CC-Link **Programless** data direct type type input input type type Type LECP1 Series LECPA CC-Link direct Capable of setting up operation (step data) Value (Step data) Operation by Features

atures	controller	input	without using a PC or teaching
mpatible motor		Step motor (Servo/24 VDC)	

Maximum number of step data 64 points 14 points Power supply voltage 24 VDC Reference page Page 560 Page 600 Page 576 Page 590

Cor

pulse signals