Electric Actuator/Slider Type **Belt Drive** (**(, FM**) ₁₁

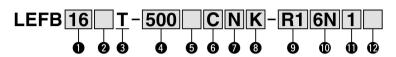
Applicable to the LEC□ series

LEFB Series LEFB16, 25, 32

Refer to page 91-1 for the communication protocols EtherCAT®. EtherNet/IP™, PROFINET, DeviceNet™, and IO-Link.

How to Order

The belt drive actuator cannot be used vertically for applications.



Size 16

32

| 3 Equ | uivalent lead [mm] |
|--------------|--------------------|
| Т | 48 |
| | 40 |

A Stroke [mm]

| • | oko [mm] |
|------|----------|
| 300 | 300 |
| to | to |
| 2000 | 2000 |
| | |

* Refer to the applicable stroke table.

6 Motor option

| Nil | Without option |
|-----|----------------|
| В | With lock |

6 Auto switch mounting bracket*

| Nil | None |
|-----|-----------------------|
| С | With 1 pc. (Included) |

- * Excluding the LEF16
- * If 2 or more are required, please order them separately. (Part no.: LEF-D-2-1 For details, refer to page 112-1.)
- * Order auto switches separately. (For details, refer to pages 112-2 and 112-3.)
- * If "Nil" is selected, the auto switch mounting bracket cannot be secured.

Grease application (Seal band part)

| Nil | With | | | | | | |
|-----|--------------------------------|--|--|--|--|--|--|
| N | Without (Roller specification) | | | | | | |
| | | | | | | | |

Positioning pin hole

| • | Positioning pin noie | | | | | | | | |
|---|----------------------|----------------------------|------------------|--|--|--|--|--|--|
| | Nil | Housing B bottom* | Housing B bottom | | | | | | |
| | К | Body bottom 2 locations | Body bottom | | | | | | |

* Refer to the body mounting example on page 114 for the mounting method.

2 Motor type

| Symbol | Type | | Compatible | | |
|--------|------------------------------|--------|------------|--------|-----------------------------------|
| | Туре | LEFB16 | LEFB25 | LEFB32 | controller/driver |
| Nil | Step motor (Servo/24 VDC) | • | • | • | LECP6 LECP1 LECPA LECPMJ |
| A | Servo motor (24 VDC) | • | • | _ | LECA6 |

[CE-compliant products]

(1) EMC compliance was tested by combining the electric actuator LEF series and the controller LEC series.

The EMC depends on the configuration of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore, conformity to the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result, it is necessary for the customer to verify conformity to the EMC directive for the machinery and equipment as a whole.

- 2 For the servo motor (24 VDC) specification, EMC compliance was tested by installing a noise filter set (LEC-NFA). Refer to page 568 for the noise filter set. Refer to the LECA series Operation Manual for installation.
- 3 CC-Link direct input type (LECPMJ) is not CE-compliant.

[UL-compliant products]

When conformity to UL is required, the electric actuator and controller/driver should be used with a UL1310 Class 2 power supply.

| Applicable Stroke Table •: Standar | | | | | | | | tandard | | | | |
|------------------------------------|-----|-----|-----|-----|-----|-----|------|---------|------|------|------|---|
| Stroke | 300 | 500 | 600 | 700 | 800 | 900 | 1000 | 1200 | 1500 | 1800 | 2000 | |
| LEFB16 | • | • | • | • | • | • | • | | | | _ | l |
| LEFB25 | • | • | • | • | • | • | • | • | • | • | • | l |
| LEFB32 | • | • | • | • | • | • | • | • | • | • | • | l |

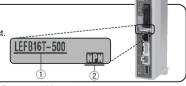
* Please consult with SMC for non-standard strokes as they are produced as special orders.

The actuator and controller/driver are sold as a package.

Confirm that the combination of the controller/driver and the actuator is correct.

<Check the following before use.>

- 1) Check the actuator label for model number. This matches the controller/driver.
- ② Check Parallel I/O configuration matches (NPN or PNP).



* Refer to the Operation Manual for using the products. Please download it via our website, http://www.smcworld.com